



Automated extraction of Soil Line and Vegetation Features from satellite imagery

Thanigai Vaasan / Hannover / 18th November 2010

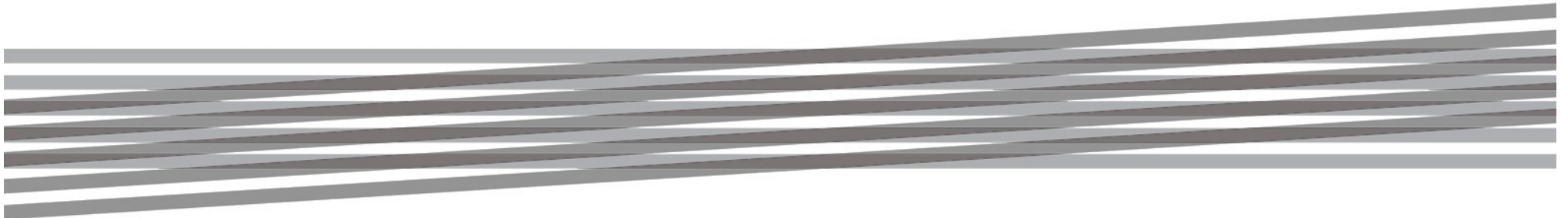


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Objective

- > To design and implement an automated algorithm to determine
 - > Soil Line attributes – Slope and Intercept
 - > Coordinates
 - > Full Canopy Point
 - > Dark Object Point
 - > Bright Object Point (experimental)
- > To visualize the results for manual verification

Approach

- > Soil line can be drawn by hand with academic experience
- > Some basic aspects of this experience like

Academic Tools

- > Pure Mathematics
 - > Cartesian Geometry
 - > Trigonometry
 - > Linear Algebra
- > Statistics
 - > Linear Regression
- > Agriculture
 - > Interpretation of the results

Computational Tools

- > C++
 - > Automated algorithm
- > Gnuplot
 - > Visualization of the results

Method

- > Pre-processing
 - > Quantize dataset
 - > Removal of duplicate points
- > Processing
 - > Extract Soil Line and Vegetation Features
- > Post-processing
 - > Save soil line and features file
 - > Generate soil line and features plot

Extraction of DN values

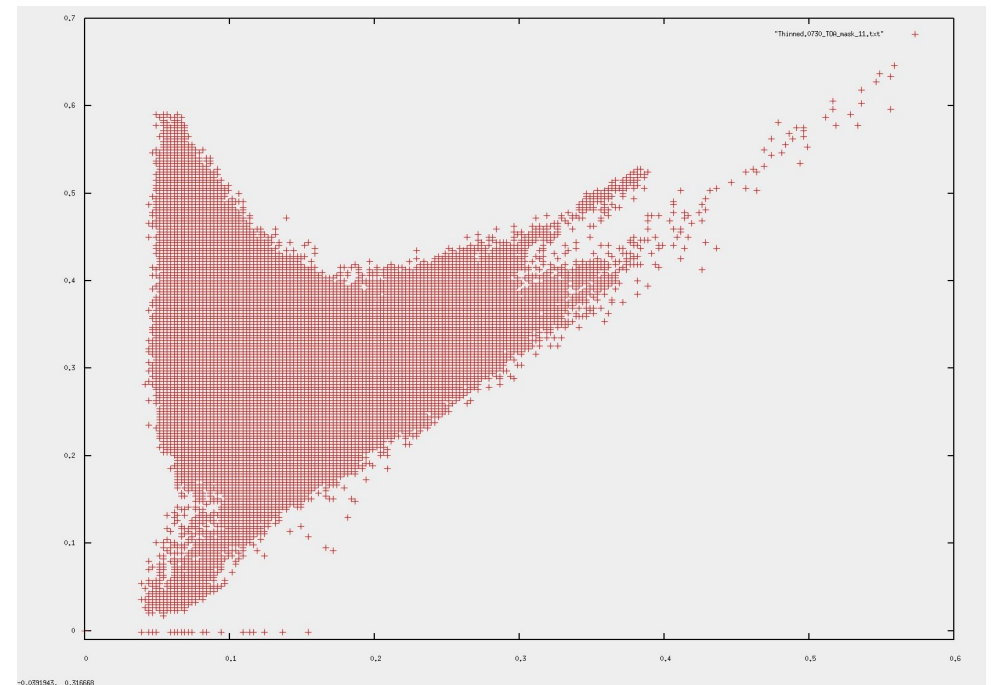
- > Extract DN values of the Red and NIR Channels of an image



0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
2.7139106E-01	3.2838097E-01
2.7139106E-01	3.3149508E-01
2.6639500E-01	3.2215273E-01
2.5640285E-01	3.1281036E-01
2.7139106E-01	3.2526684E-01
2.8887731E-01	3.4706563E-01
2.7638713E-01	3.2526684E-01
2.7139106E-01	3.1903860E-01

Red vs NIR plot

0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
0.0000000E+00	0.0000000E+00
2.7139106E-01	3.2838097E-01
2.7139106E-01	3.3149508E-01
2.6639500E-01	3.2215273E-01
2.5640285E-01	3.1281036E-01
2.7139106E-01	3.2526684E-01
2.8887731E-01	3.4706563E-01
2.7638713E-01	3.2526684E-01
2.7139106E-01	3.1903860E-01



Quantization of dataset

- > Constraining a continuous set of values to a discrete set
- > Shape of Red vs NIR plot remains the same
 - > Results remain the same
- > Necessary to streamline the feature extraction process

Duplicate points problem

- > Remove duplicate points from the dataset
 - > Generates Thinned dataset with unique values
 - > Greatly reduces the dataset size

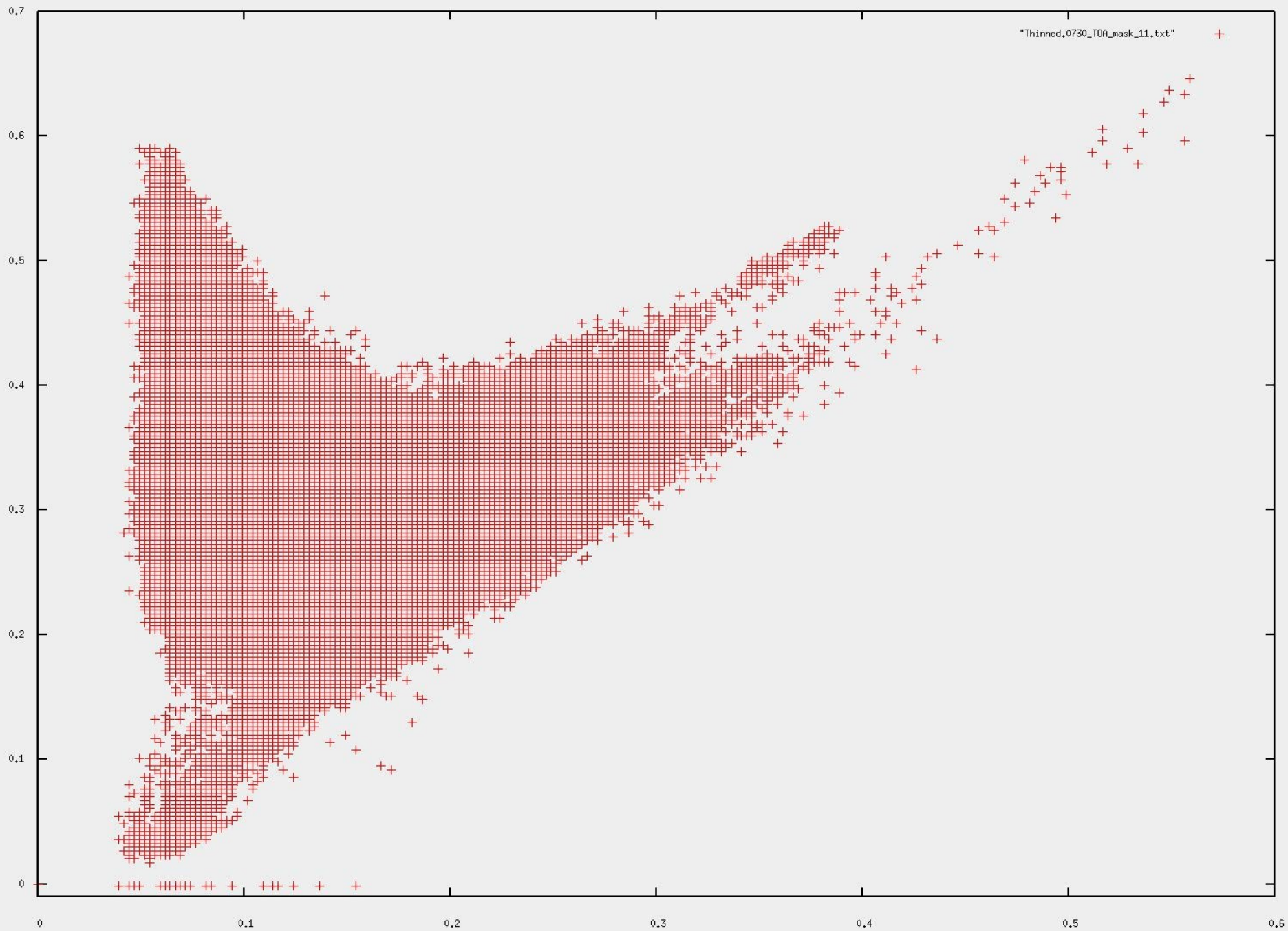
Example:

Size of an original Red vs NIR text file – 23.9 MB

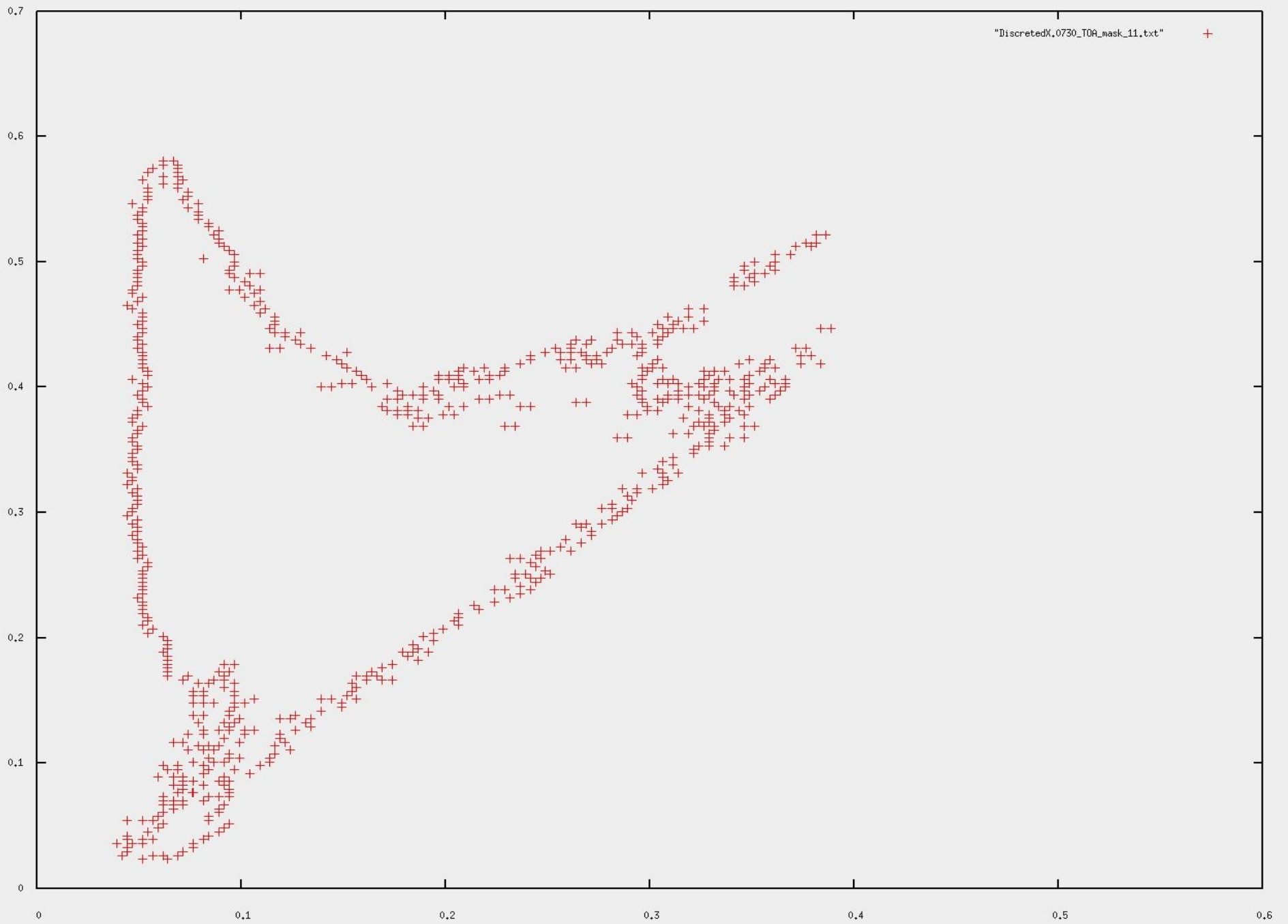
Size of the Thinned Red vs NIR text file – 317 KB

Preparation

- > Determine difference between two closest abscissae
- > Determine difference between two closest ordinates
- > Sort dataset along ascending ordinates and then re-sort along ascending abscissae
- > Discretize the dataset along X axis
- > Remove points lower than the valid Dark Object Point



-0.0391943, 0.316668

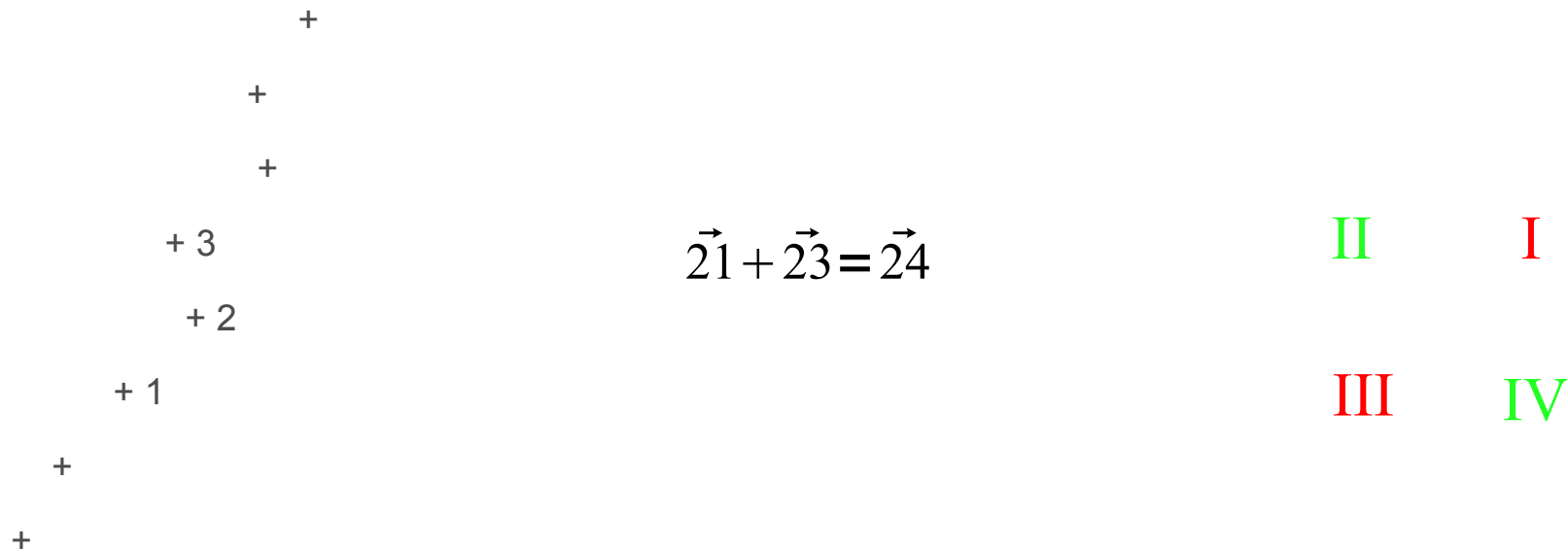


Main Process

- > Gather all points from the right-sided boundary which validates
 - > Three point facing
 - > $\vec{21} + \vec{23} = \vec{24}$
 - > The unit vector of addition must be along either II and IV quadrants
 - > Three point smoothness
 - >

Main Process

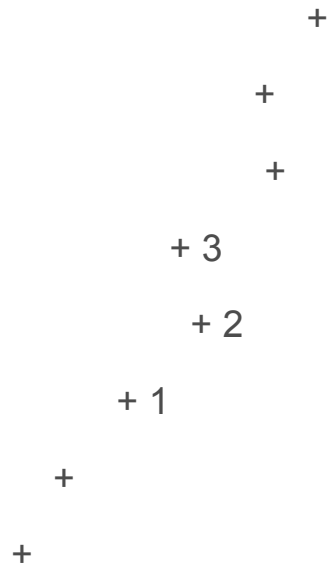
- > Gather all points from the right-sided boundary which validates
 - > Three point facing



The point 2 is valid if the unit vector $\hat{2}_4$ is along II or IV quadrants

Main process

- > Gather all points from the right-sided boundary which validates
 - > Three point smoothness



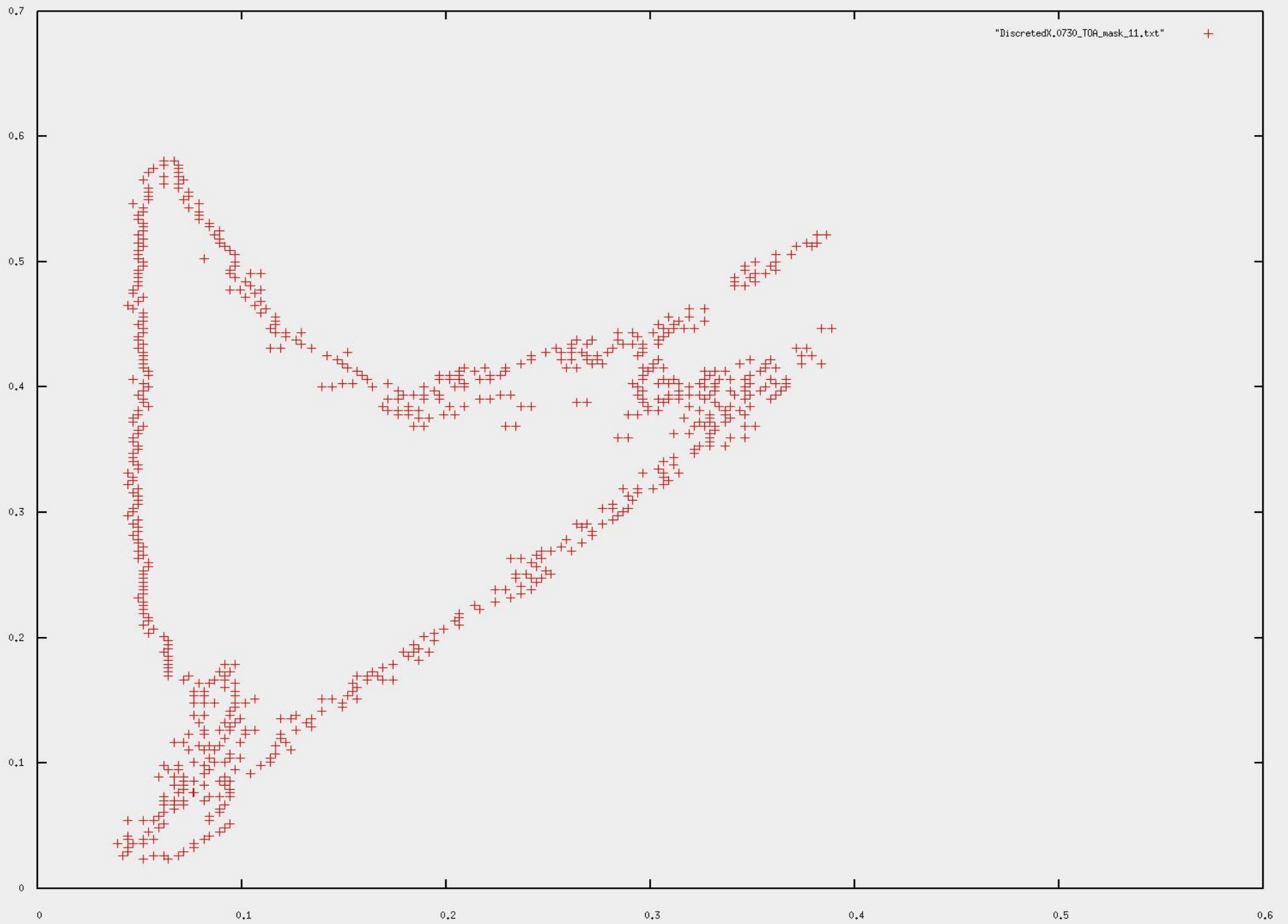
$$\alpha = \cos^{-1} \left(\frac{\vec{21} \cdot \vec{23}}{|\vec{21}| |\vec{23}|} \right)$$

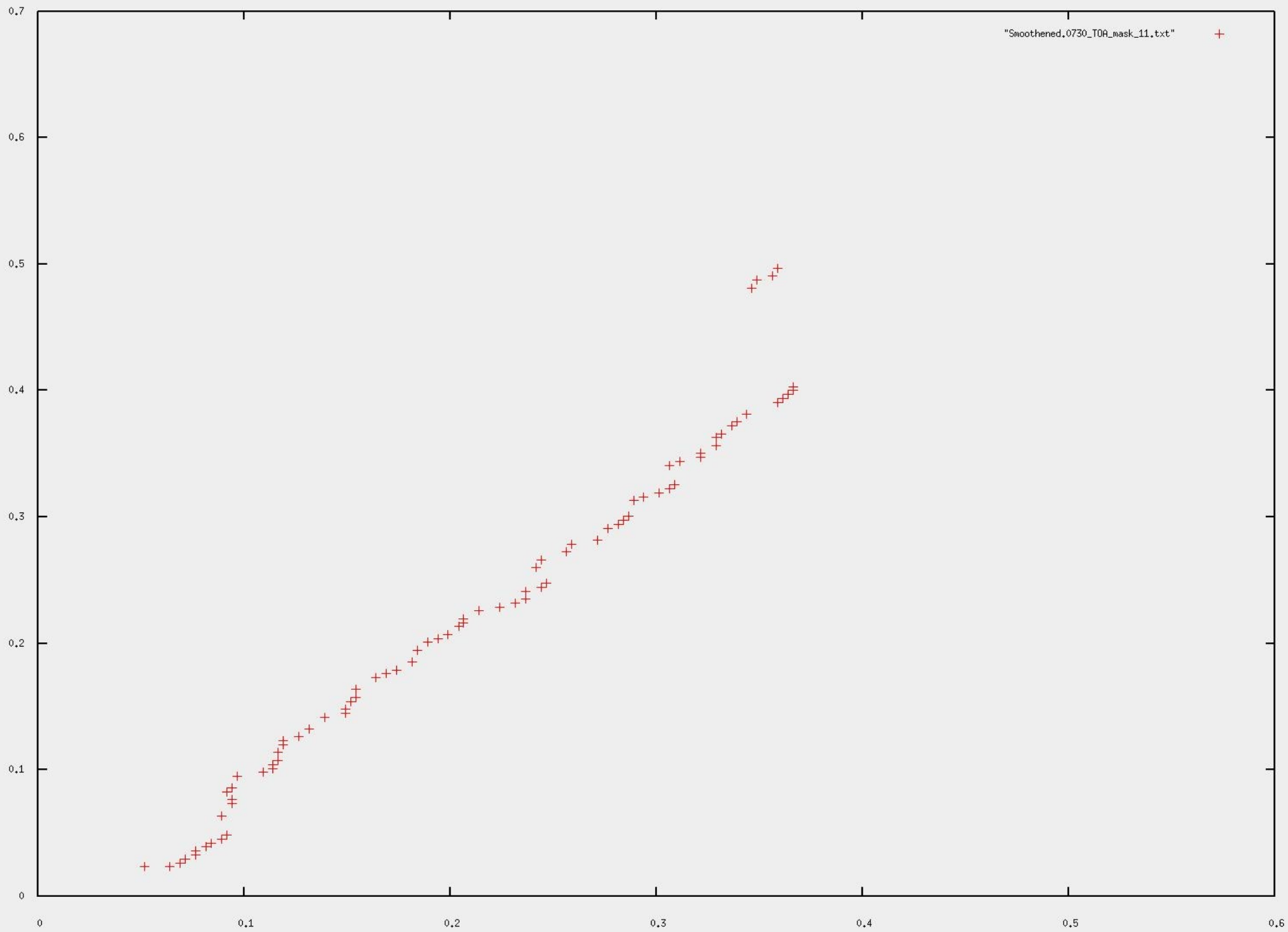
$$0 \leq \alpha \leq \pi$$

$$\forall \alpha \leq \frac{\pi}{2} \Rightarrow \textit{Sharp}$$

$$\forall \alpha > \frac{\pi}{2} \Rightarrow \textit{Smooth}$$

The point 2 is valid , if $\alpha > \frac{\pi}{2}$



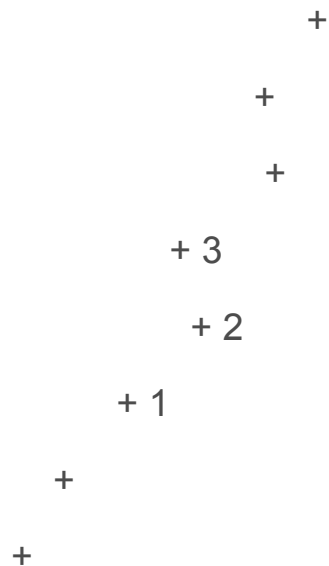


Main process

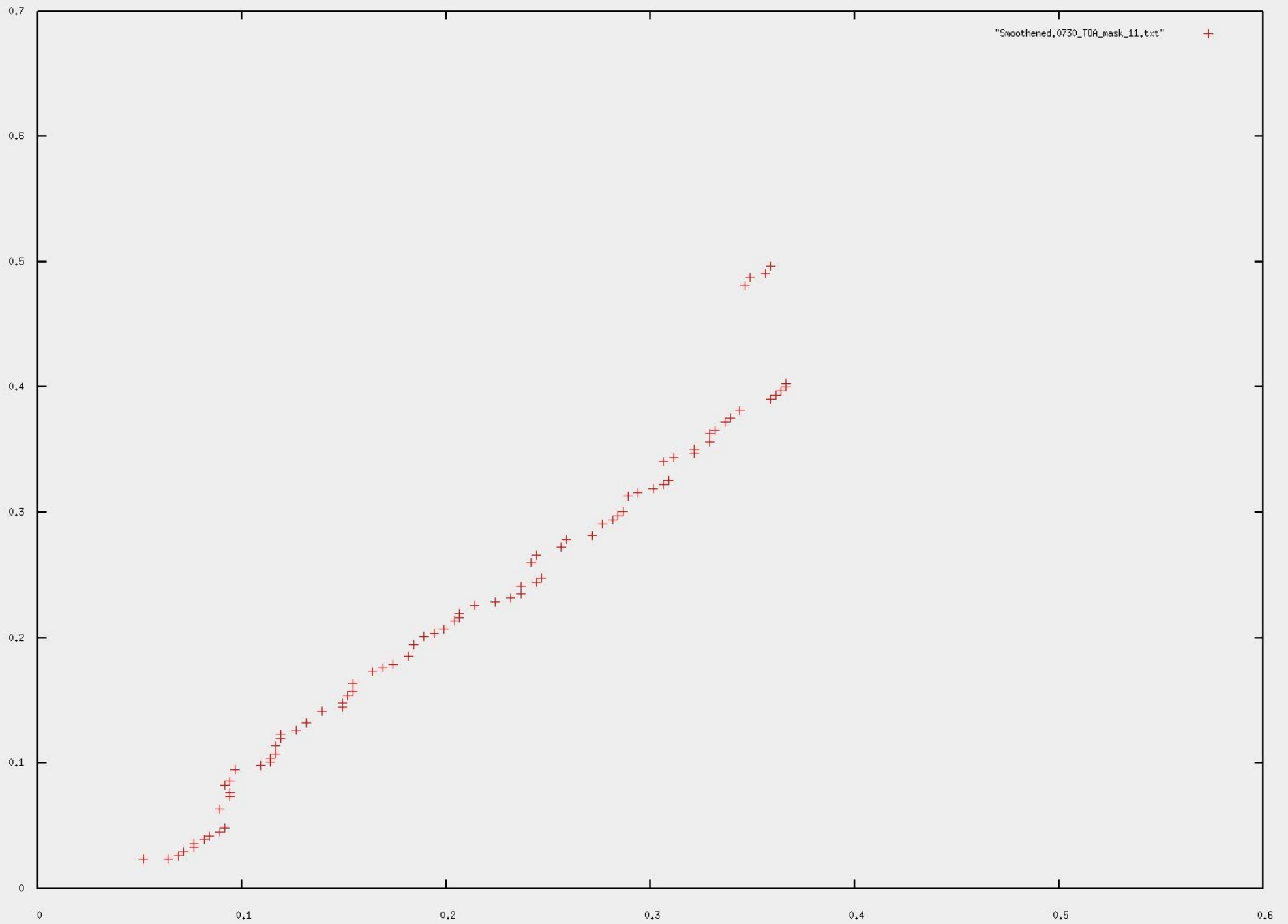
- > Determine Dark Object Point (DOP)
 - > DOP Nir = Ordinate of the first point in the Smoothened dataset
 - > Collect all points whose ordinates are equal to DOP Nir
 - > Potential DOP list
 - > DOP Red = Abscissa of the centermost point in Potential DOP list
- > Erase Potential DOPs
 - > Erase all points whose ordinates equal DOP Nir

Main process

- > Gather all points from the right-sided boundary which ensure
 - > Three point positive slope transition

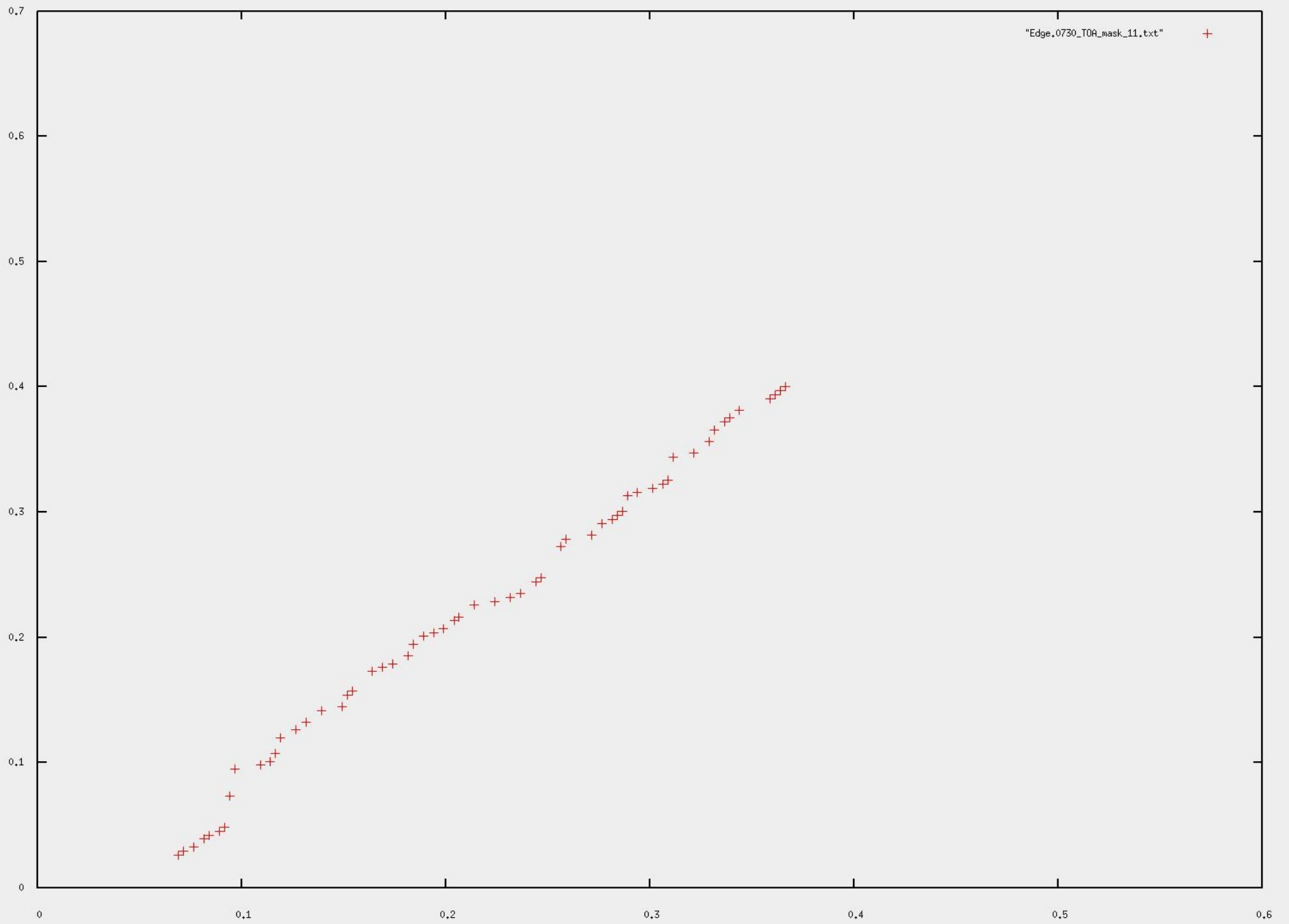


- > Collect points which correspond to consecutive positive slopes
- > Intuitively ignore points which make infinite or negative slopes



"Smoothered.0730_T0R_nask_11.txt"

+



-0.0346217, 0.248811

Soil Line coefficients

- > Gather Soil Line points
 - > Determine the line of regression for the points in Edge dataset
 - > Collect the points which lie above the line of regression
 - > Those points correspond to the Soil Line dataset

- > Soil Line Coefficients
 - > Determine the line of regression for the Soil Line dataset
 - > The coefficients of regression denote the Slope and Intercept of the Soil Line

Vegetation Features

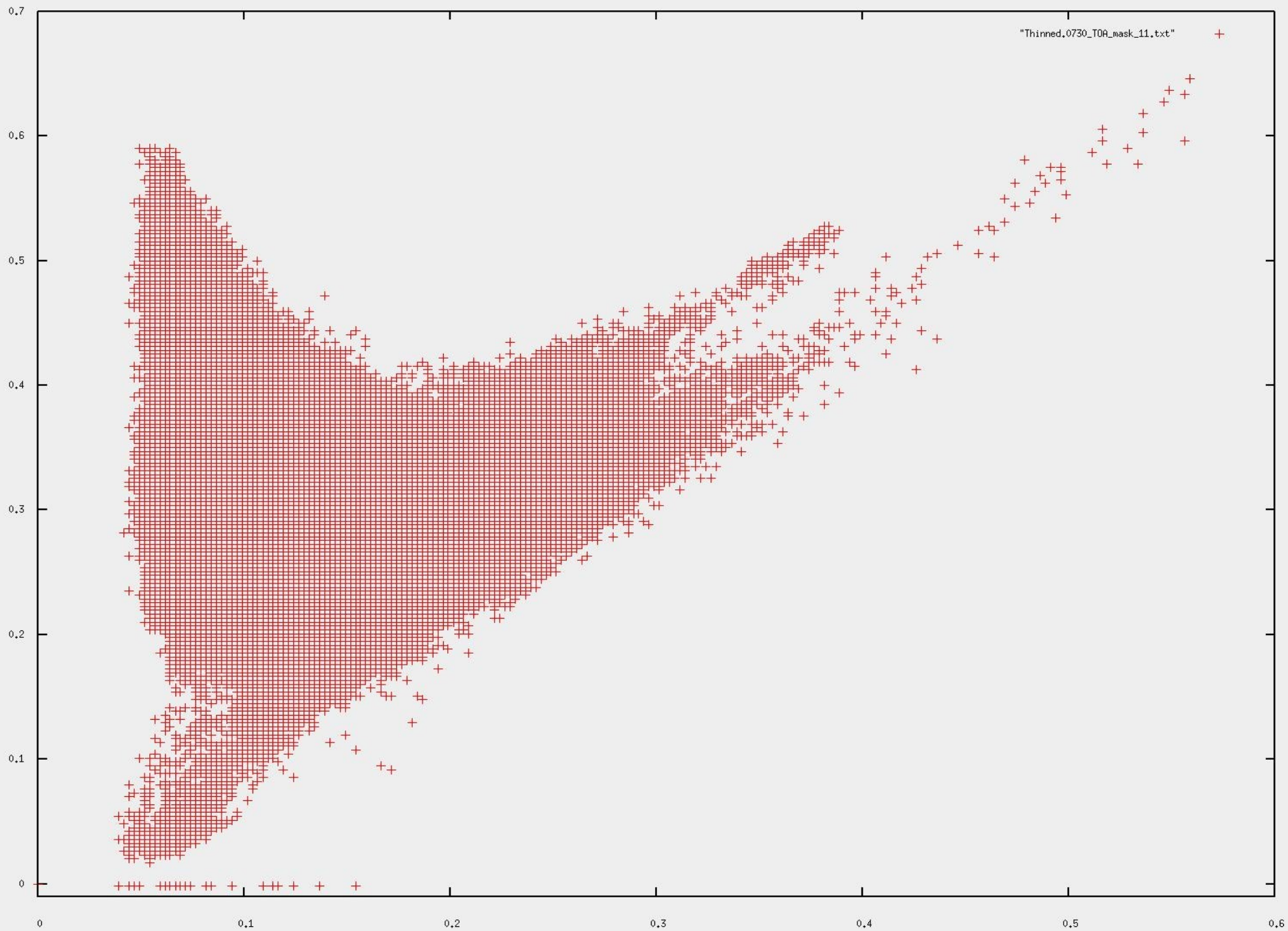
- > Extract Tasseled Cap Points
 - > Similar methodology as Soil Line Extraction but rules are different
 - > FCP is determined using an independent method as the last step of the extraction of Tasseled Cap Features
 - > The determined FCP is validated w.r.t. several special cases
- > Soil line features are saved in Features.ImageBaseName.txt

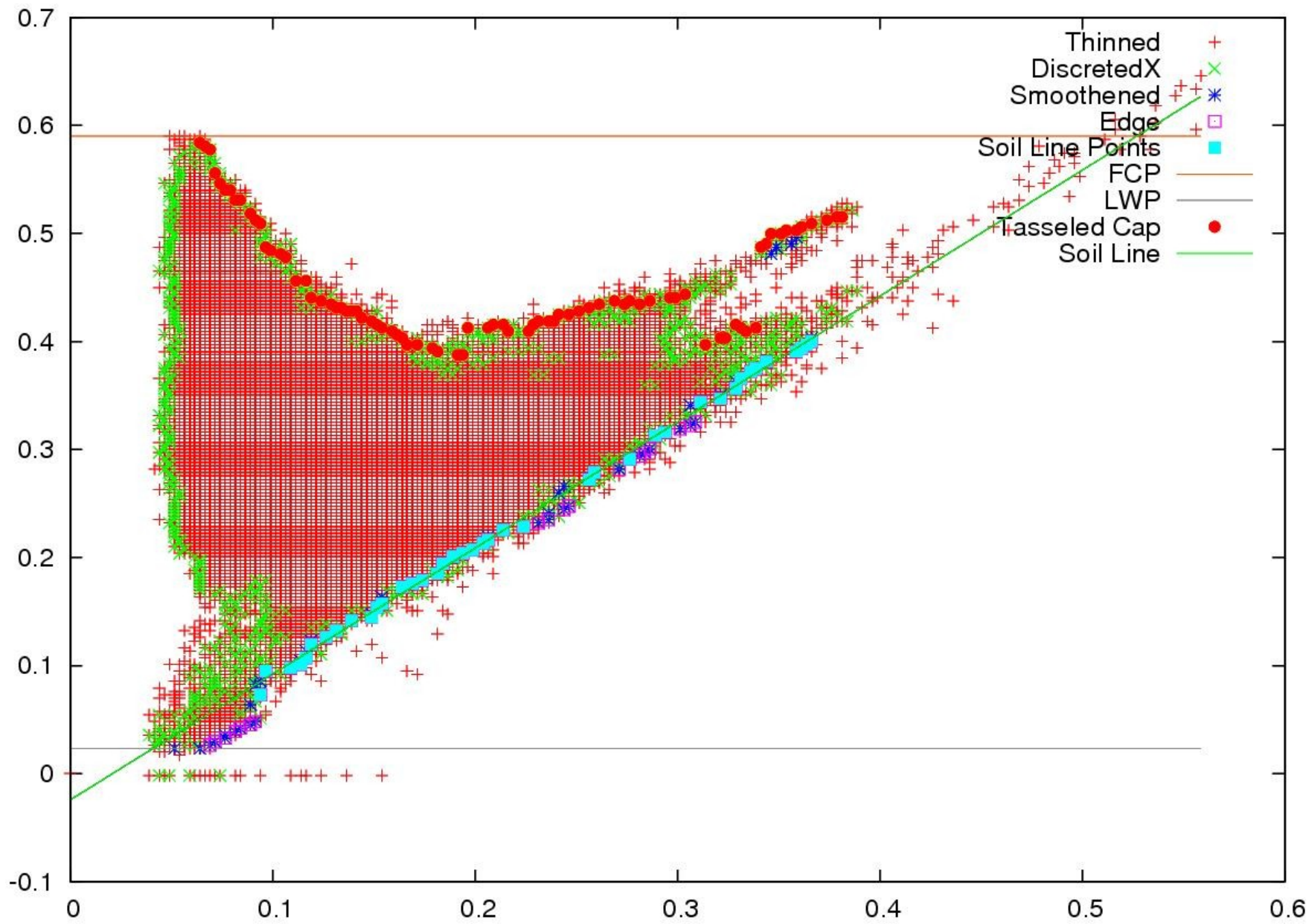
Slope 1.53551

Intercept -0.0762188

DOP 0.0638483 0.0317913

FCP 0.109509 0.661583





Applications

- > Ground Cover Map Generation
- > Dark Object Subtraction
- > Other possible applications (in research)
 - > Land Cover classification
 - > Field Boundary Extraction

Limitations

- > Extremely high vegetation
 - > FCP is reliable
 - >
- > Extremely low vegetation
 - > Soil Line is reliable
 - >

Conclusion

- > An algorithm to fully automate the extraction of soil line and corresponding vegetation features has been achieved
- > Limitations has to be studied thoroughly to
 - > Enhance the results
 - > Define an indeterminable state for the results
- > Further possible applications has to be identified