Ground-breaking versatility

The UltraCam Panther defines a new class of 3D capture systems.







The UltraCam Panther is currently under redesign and will be coming back allowing even more efficient 3D reality capture from every perspective.



Reliable partner on the road

With over 5 million linear kilometers on the road collected and a history of more than nine years, the UltraCam Mustang has proven itself as a state-ofthe-art mobile mapping system.

Number of

cameras:

9

Field of view:

360° x 256°

Max, frame rate:

8 frames/second

CAMERA & PANORAMIC HEAD

Sensor type	Global-Shutter CCD
Sensor size	2752 x 2200 pixels
Pixel size	4.54 µm
F-number	F2.8 - F9.0, fixed focus
Lens	8.0 mm p-iris, diffraction-limited
Depth of field	1 m to infinity (@ \geq F4)
Radiometry	Bayer pattern, 12 bit raw; average (lossless) compression ratio 1:1.5

GLOBAL POSITIONING	Туре	GNSS/INS receiver, GPS L1/L2/L2C, GLONASS L1/L2, SBAS and L-Band
	Antenna	Dual frequency GPS and GLONASS Pinwheel
	Frequency	100 Hz (IMU/INS), 20 Hz (GNSS)
	Gyroscope performance	Input range ± 375 deg/sec
	Accelerometer performance	Range ± 10 g, Bias 50 mg, Scale Factor 4000 ppm
	Post-processing accuracy RMS	0.020 m horizontal, 0.020 m vertical, 0.008 degrees pitch/roll, 0.013 degrees heading
	Synchronization	Time stamped data

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GEOMETRY Type Field of view Channels Data rate Useable range Accuracy Rotation speed	Туре	Multi beam rotating LiDAR
	Field of view	360° horizontal x 40° vertical
	Channels	32
	Data rate	700.000 points/second
	Useable range	70 m
	Accuracy	+/- 2 cm (@ 25 m)
	Rotation speed	10 Hz (max. 1200 rpm)





Sensor resolution:

54 Megapixels

Distance between

optical centers:

~10 cm Synchronisation:

frame-by-frame,

time stamped data



Total power consumption: 660 W (system powered by car battery)



Dimensions: 134 x 63 x 41 cm (hinged) 110 x 63 x 142 cm (upright)



Temperature: -10°C to +40°C (operation) -10°C to +70°C (storage)